

Combining Widening and Acceleration in Linear Relation Analysis

(work in progress)

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VERIMAG



Motivation

Linear Relation Analysis (LRA)

- **widening:**

- approximate results,
- can be arbitrarily refined by delaying the widening
- but delaying the widening is expensive

- **acceleration:**

- Boigelot/Wolper, Common/Jurski, Finkel/Sutre/Leroux
- compute the exact effect of loops
- only works for a quite restricted class of programs, high complexity

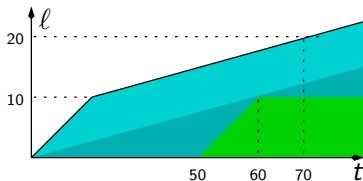
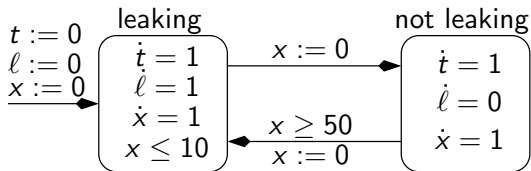
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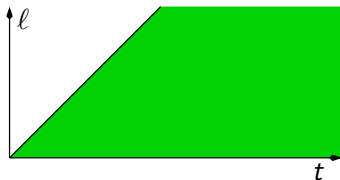
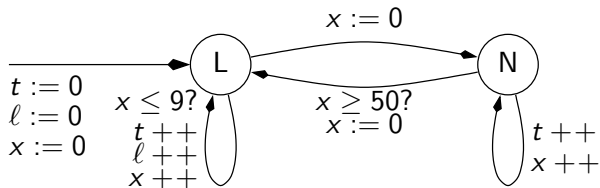
A motivating example: the gaz burner

Continuous behaviour



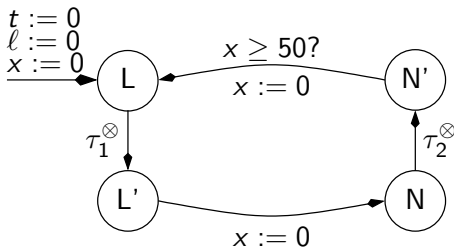
The gaz burner (cont.)

Discretizing



The gaz burner (end.)

We want to replace the loops ...



Simple loops

We want to characterise $P = \tau^*(P_0)$, where :

$$\tau(x) = \text{if } Ax \leq B \text{ then } Cx + D \text{ else } x$$

with (A, B) “guard” and (C, D) “action”

$$x \in P \Leftrightarrow \exists i \in \mathbb{N}, \exists x_0 \in P_0, x = \tau^i(x_0)$$

i.e., if we define the sequence (x_k) by $x_i = C^i x_0 + \sum_{j=0}^{i-1} C^j D$:

$$x \in \tau^*(x_0) \Leftrightarrow \exists i \in \mathbb{N}, x = x_i \text{ and } \forall j \in [0, i-1], Ax_j \leq B$$

Some simple cases

Computing C^k is too expensive

- [Leroux02] : the linear functions $\lambda x. CX + D$ with $\{C^k, k \in \mathbb{N}\}$ finite are *effectively* Presburger-definable.
- Simplest case: $C = \text{Id}$ (“translation”)
- Some cases hwre $C^2 = C$ (incrementation / assignment to constant).

Single translation loop

$$\tau(x) = \text{if } Ax \leq B \text{ then } x + D \text{ else } x$$

(obvious) **Proposition** If $C = Id$, then $x \in \tau^*(P_0)$ iff

$$\exists i \in \mathbb{N}, \exists x_0 \in P_0, Ax_0 \leq B, A(x - D) \leq B, x = x_0 + iD$$

Abstract acceleration

$$\tau^\otimes(P_0) = \bigsqcup \{x \mid \exists i \in \mathbb{Q}, \exists x_0 \in P_0, \\ Ax_0 \leq B, A(x - D) \leq B, x = x_0 + iD\}$$

Computation

$$\tau^\otimes(P_0) = ((P_0 \cap (Ax \leq B)) \nearrow D) \cap (A(x - D) \leq B)$$

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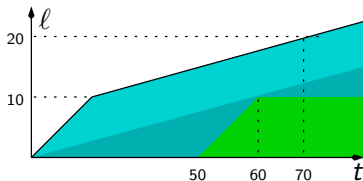
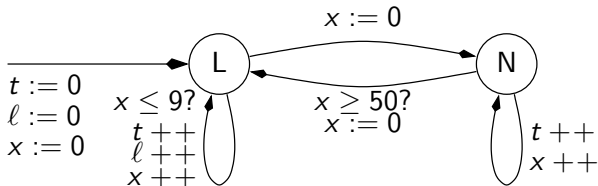
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Computation

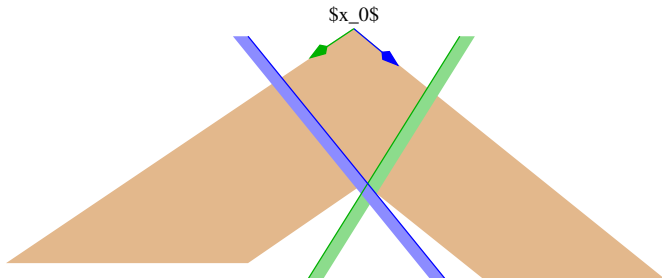
$$\tau^\otimes(P_0) = ((P_0 \cap (Ax \leq B)) \nearrow D) \cap (A(x - D) \leq B)$$

Ex.: gaz burner



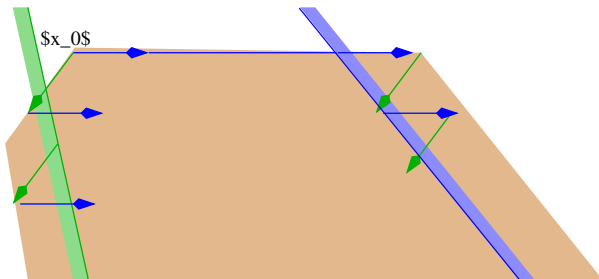
Two loops - First remarks

$(\tau_1 + \tau_2)^*(P_0)$ is not necessarily **convex** :

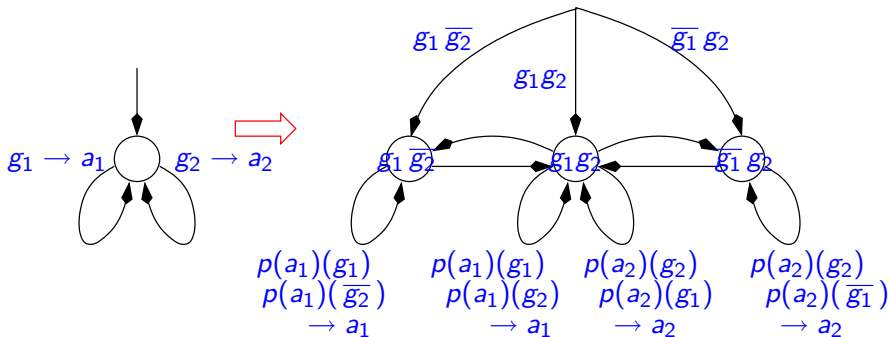


Two loops - First remarks

There can be quite complex **oscillations**



Several loops: partitioning



(at least conceptually)

Two simple translation loops – results

Simple translation loops: simple guards $g = ax \leq b$

$$\tau_i(x) = \text{if } g_i \text{ then } x + D_i \text{ else } x, \quad i = 1, 2$$

We know how to abstractly accelerate two simple loops as long as both guards are satisfied (not completely obvious)

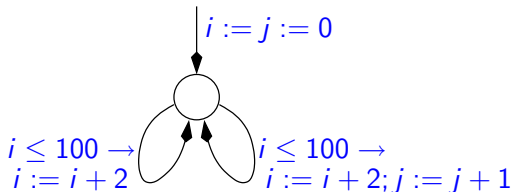
Result: if $P_0 \subseteq g_1 \cap g_2$ then

$$(\tau_1 + \tau_2)^{\otimes} (P_0) \cap g_1 \cap g_2 = (P_0 \nearrow \{D_1, D_2\}) \cap g_1 \cap g_2$$

Old Cousot&Halbwachs78 example

```

i:=j:=0;
while i<= 100 do
1  if ? then i:=i+2
   else i:=i+2; j:=j+1
   fi
od
    
```

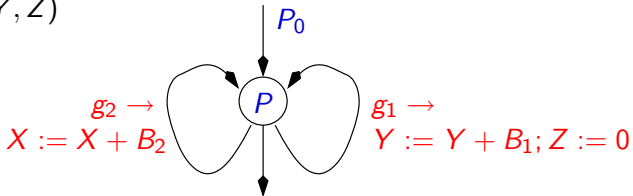


Immediate result at 1:

$$\begin{aligned}
 (0, 0) &\nearrow \{(2, 0), (2, 1)\} \cap (i \leq 100) \\
 &= 0 \leq 2j \leq i \leq 100
 \end{aligned}$$

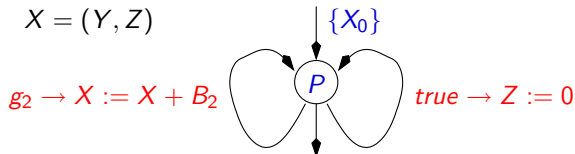
Two loops with reset (or constant assignments)

$X = (Y, Z)$

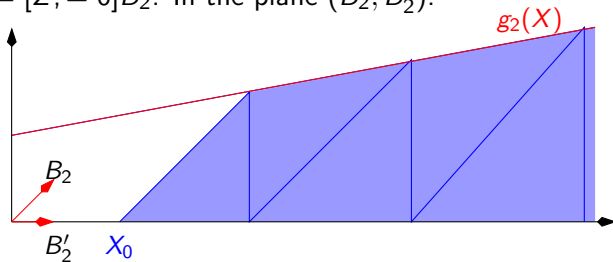


Unconditional simple reset

$$X = (Y, Z)$$

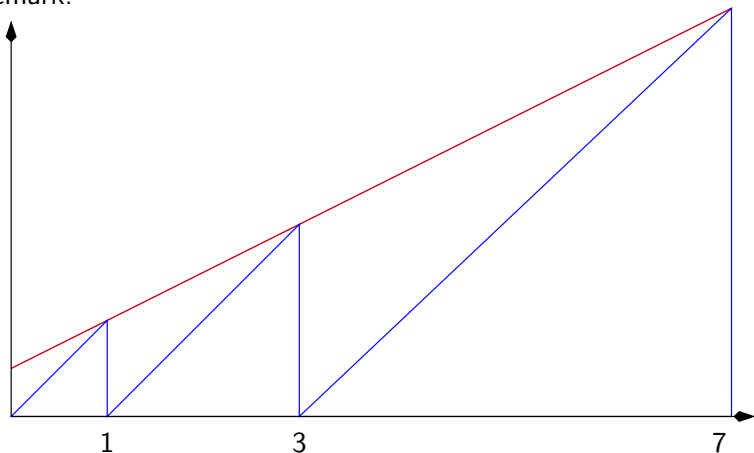


Let $B'_2 = [Z; = 0]B_2$. In the plane (B_2, B'_2) :



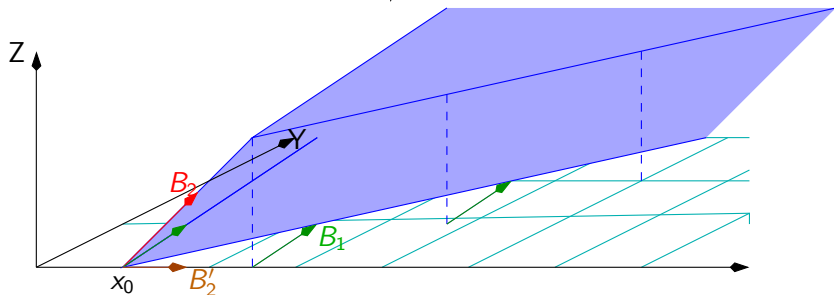
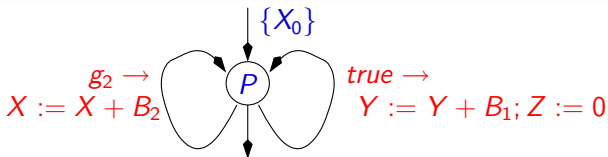
$$P = \{X_0\} \nearrow \{B_2, B'_2\} \cap g_2$$

Remark:



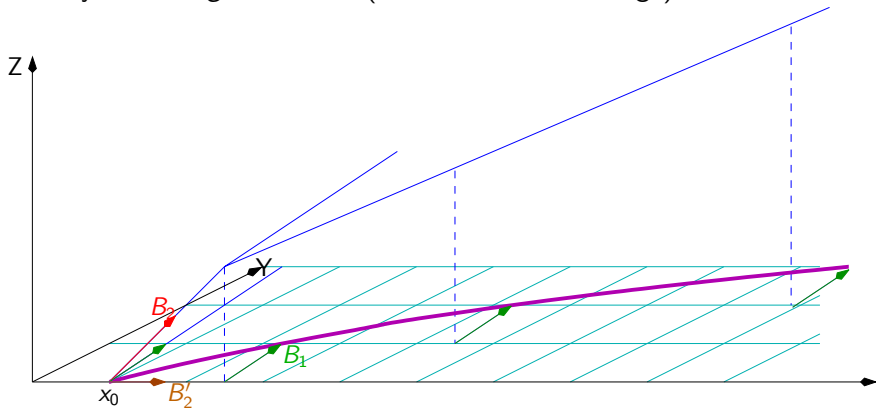
The exact set is not semi-linear

Unconditional translation/reset

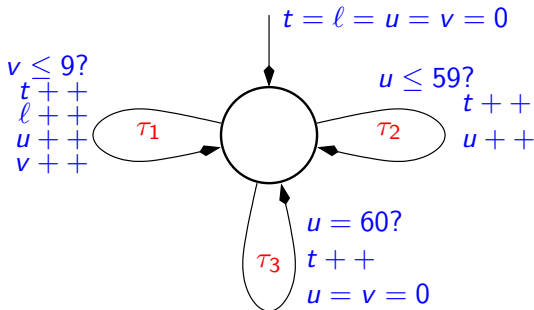


$$P = P_0 \nearrow \{B_1, B_2, k_{\max} B'_2 + B_1\} \cap g_2$$

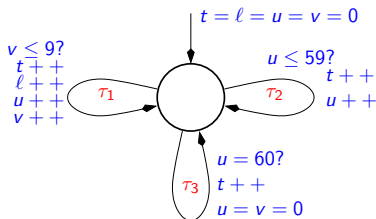
Only works if $g_2 = Z \leq C$ (modulo variable change)



An other (more difficult) version of the gaz burner



Let $X = (t, l, u, v)$, $Z = \{u, v\}$. $X_0 = (0, 0, 0, 0)$.



We compute

$$F_1 = (\tau_1 + \tau_2)^*(X_0) = \{\ell = v, t = u, 0 \leq \ell \leq 10, \ell \leq t \leq 60\}$$

(two simple translation loops).

Then, $\tau_3(F_1) = \{u = v = 0, t = 60, 0 \leq \ell \leq 10\}$, thus

$$D_3 + k_1^{\max} D_1^Y = (0, 60, 0, 0) \text{ and } D_3 + k_2^{\max} D_2^Y = (0, 60, 10, 0)$$

And we finally get :

$$F(X_0) = \{\ell \geq v, u \leq 60, 0 \leq v \leq 10, u \geq v, u + 6\ell \leq t + 6y\}$$

whose projecton onto $\{t, \ell\}$ gives $\{t + 50 \geq 6\ell, \ell \geq 0, t \geq \ell\}$.